Sparse Markov Models for High-Dimensional Inference

Guilherme Ost

Federal University of Rio de Janeiro

CYU ECODEP

Jun, 2022

Joint work with



D.Y. Takahashi (Brain Institute/UFRN)

Transition probabilities: $p(x) = \mathbb{P}(X_t = 1 | X_{t-d:t-1} = x)$ for $x \in \{0, 1\}^d$.

Transition probabilities: $p(x) = \mathbb{P}(X_t = 1 | X_{t-d:t-1} = x)$ for $x \in \{0, 1\}^d$.

Classical question: how to estimate the transition probabilities p(x) given the data?

Transition probabilities: $p(x) = \mathbb{P}(X_t = 1 | X_{t-d:t-1} = x)$ for $x \in \{0, 1\}^d$.

Classical question: how to estimate the transition probabilities p(x) given the data?

The MLE of p(x) computed from the data is given by

$$\hat{p}_n(x) = \frac{N_n(x,1)}{N_n(x,0) + N_n(x,1)} = \frac{N_n(x,1)}{\bar{N}_n(x)},$$

where $N_n(x, b) = |\{d + 1 \le t \le n : X_{t-d:t-1} = x, X_t = b\}|.$

Transition probabilities: $p(x) = \mathbb{P}(X_t = 1 | X_{t-d:t-1} = x)$ for $x \in \{0, 1\}^d$.

Classical question: how to estimate the transition probabilities p(x) given the data?

The MLE of p(x) computed from the data is given by

$$\hat{p}_n(x) = \frac{N_n(x,1)}{N_n(x,0) + N_n(x,1)} = \frac{N_n(x,1)}{\bar{N}_n(x)},$$

where $N_n(x, b) = |\{d + 1 \le t \le n : X_{t-d:t-1} = x, X_t = b\}|.$

Focus on the high-dimensional setting: $d = d_n$ and $p(x) = p_n(x)$.

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

2. For $\hat{p}_n(x)$ to have any meaning, we need that $\bar{N}_n(x) \ge 1$.

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

2. For $\hat{p}_n(x)$ to have any meaning, we need that $\bar{N}_n(x) \ge 1$. By ergodicity,

 $\bar{N}_n(x) \approx n \mathbb{P}(X_{1:d} = x).$

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

2. For $\hat{p}_n(x)$ to have any meaning, we need that $\bar{N}_n(x) \ge 1$. By ergodicity,

$$\bar{N}_n(x) \approx n \mathbb{P}(X_{1:d} = x).$$

If the transition probabilities are bounded below from zero, then $\exists c > 0$ such that

$$\mathbb{P}(X_{1:d} = x) < e^{-cd}.$$

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

2. For $\hat{p}_n(x)$ to have any meaning, we need that $\bar{N}_n(x) \ge 1$. By ergodicity,

$$\bar{N}_n(x) \approx n \mathbb{P}(X_{1:d} = x).$$

If the transition probabilities are bounded below from zero, then $\exists c > 0$ such that

$$\mathbb{P}(X_{1:d} = x) < e^{-cd}.$$

Hence, we need $1 \le ne^{-cd}$ implying that $d \le C \log_2 n$.

There are two related ways to convince of this:

1. The number of free parameters $Dim_{MC}(d) = 2^d$ grows exponentially with d.

2. For $\hat{p}_n(x)$ to have any meaning, we need that $\bar{N}_n(x) \ge 1$. By ergodicity,

$$\bar{N}_n(x) \approx n \mathbb{P}(X_{1:d} = x).$$

If the transition probabilities are bounded below from zero, then $\exists c > 0$ such that

$$\mathbb{P}(X_{1:d} = x) < e^{-cd}.$$

Hence, we need $1 \le ne^{-cd}$ implying that $d \le C \log_2 n$. Need to seek for sparse Markov chains!

Minimal Markov Models (MMM) are Markov chains of order d such that there exist a partition C_1, \ldots, C_K of $\{0, 1\}^d$ with the property that

p(x) = p(y) if and only if $x, y \in C_i$.

Minimal Markov Models (MMM) are Markov chains of order d such that there exist a partition C_1, \ldots, C_K of $\{0, 1\}^d$ with the property that

p(x) = p(y) if and only if $x, y \in C_i$.

The dimension of a MMM is $Dim_{MMM}(d) = K$. Sparse when $K \ll 2^d$.

Minimal Markov Models (MMM) are Markov chains of order d such that there exist a partition C_1, \ldots, C_K of $\{0, 1\}^d$ with the property that

p(x) = p(y) if and only if $x, y \in C_i$.

The dimension of a MMM is $Dim_{MMM}(d) = K$. Sparse when $K \ll 2^d$.

Variable length Markov chains (VLMC) are MMM for which the partition C_1, \ldots, C_K is "given by a irreducible tree".

Minimal Markov Models (MMM) are Markov chains of order d such that there exist a partition C_1, \ldots, C_K of $\{0, 1\}^d$ with the property that

p(x) = p(y) if and only if $x, y \in C_i$.

The dimension of a MMM is $Dim_{MMM}(d) = K$. Sparse when $K \ll 2^d$.

Variable length Markov chains (VLMC) are MMM for which the partition C_1, \ldots, C_K is "given by a irreducible tree".

Without further hypothesis, p(x) can be estimated still only if $d \le C \log_2 n$ (by the point 2 above.)

What if $d \gg C \log_2 n$?

What if $d \gg C \log_2 n$?

Why this regime is important? Many natural phenomena have very long memory!

What if $d \gg C \log_2 n$?

Why this regime is important? Many natural phenomena have very long memory!

In this talk: we suppose $d = \beta n$ with $\beta \in (0, 1)$ and focus on another class of sparse Markov chains, called Mixture Transition Distribution (MTD) models.

MTD models have been introduced by A. Raftery ('85). For applications see A. Berchtold & Raftery ('02).

Markov chains of order d such that

$$p(x) = \lambda_0 p_0 + \sum_{j=-d}^{-1} \lambda_j p_j(x_j)$$

where: $x = (x_{-d}, ..., x_{-1})$ and

▶
$$0 \le p_0, p_j(a) \le 1$$
 for all $j \in \{-d, ..., -1\}$ and $a \in \{0, 1\}$.

•
$$\lambda_0, \lambda_1, \dots, \lambda_{-d} \in [0, 1]$$
 such that $\sum_{j=-d}^0 \lambda_j = 1$.

Markov chains of order d such that

$$p(x) = \lambda_0 p_0 + \sum_{j=-d}^{-1} \lambda_j p_j(x_j)$$

where:
$$x = (x_{-d}, ..., x_{-1})$$
 and
• $0 \le p_0, p_j(a) \le 1$ for all $j \in \{-d, ..., -1\}$ and $a \in \{0, 1\}$.
• $\lambda_0, \lambda_1, ..., \lambda_{-d} \in [0, 1]$ such that $\sum_{j=-d}^0 \lambda_j = 1$.

For each lag $j \in \{-d, \ldots, -1\}$, let $\delta_j = \lambda_j |p_j(1) - p_j(0)|$.

Markov chains of order d such that

$$p(x) = \lambda_0 p_0 + \sum_{j=-d}^{-1} \lambda_j p_j(x_j)$$

where:
$$x = (x_{-d}, ..., x_{-1})$$
 and
• $0 \le p_0, p_j(a) \le 1$ for all $j \in \{-d, ..., -1\}$ and $a \in \{0, 1\}$.
• $\lambda_0, \lambda_1, ..., \lambda_{-d} \in [0, 1]$ such that $\sum_{j=-d}^0 \lambda_j = 1$.

For each lag $j \in \{-d, \ldots, -1\}$, let $\delta_j = \lambda_j |p_j(1) - p_j(0)|$.

Denote $\Lambda = \{j \in \{-d, \dots, -1\} : \delta_j > 0\}$ (set of relevant lags).

Markov chains of order d such that

$$p(x) = \lambda_0 p_0 + \sum_{j=-d}^{-1} \lambda_j p_j(x_j)$$

where:
$$x = (x_{-d}, ..., x_{-1})$$
 and
• $0 \le p_0, p_j(a) \le 1$ for all $j \in \{-d, ..., -1\}$ and $a \in \{0, 1\}$.
• $\lambda_0, \lambda_1, ..., \lambda_{-d} \in [0, 1]$ such that $\sum_{j=-d}^0 \lambda_j = 1$.

For each lag $j \in \{-d, \ldots, -1\}$, let $\delta_j = \lambda_j |p_j(1) - p_j(0)|$.

Denote $\Lambda = \{j \in \{-d, \dots, -1\} : \delta_j > 0\}$ (set of relevant lags).

Note that $p(x) = p(x_{\Lambda})$ and $Dim_{MTD}(d) = 3|\Lambda| + 1$.

First, estimate Λ from the data. Denote $\hat{\Lambda}_n$ an estimator of Λ .

First, estimate Λ from the data. Denote $\hat{\Lambda}_n$ an estimator of Λ .

Then, compute $\hat{p}_n(x_{\hat{\Lambda}_n})$.

First, estimate Λ from the data. Denote $\hat{\Lambda}_n$ an estimator of Λ .

Then, compute $\hat{p}_n(x_{\hat{\Lambda}_n})$.

Statistical lag selection: how to estimate efficiently Λ from the data?

First, estimate Λ from the data. Denote $\hat{\Lambda}_n$ an estimator of Λ .

Then, compute $\hat{p}_n(x_{\hat{\Lambda}_n})$.

Statistical lag selection: how to estimate efficiently Λ from the data?

Remark: the behavior of $\min_{j \in \Lambda} \delta_j^2$ measures how difficult is to estimate Λ .

First, estimate Λ from the data. Denote $\hat{\Lambda}_n$ an estimator of Λ .

Then, compute $\hat{p}_n(x_{\hat{\Lambda}_n})$.

Statistical lag selection: how to estimate efficiently Λ from the data?

Remark: the behavior of $\min_{j \in \Lambda} \delta_j^2$ measures how difficult is to estimate Λ .

Indeed, lag selection is possible (in the minimax sense) only if

$$\min_{j\in\Lambda}\delta_j^2\geq C\frac{\log(n)}{n}.$$

Goal of this talk:

- to present an efficient estimator of the set of relevant lags Λ, based on a sample X_{1:n} of a MTD model with order d.
- ▶ to provide some theoretical guarantees in the high-dimensional regime $\Lambda = \Lambda_n$ and $d = d_n = \beta n$ for some $\beta \in (0, 1)$.

Goal of this talk:

- to present an efficient estimator of the set of relevant lags Λ, based on a sample X_{1:n} of a MTD model with order d.
- ▶ to provide some theoretical guarantees in the high-dimensional regime $\Lambda = \Lambda_n$ and $d = d_n = \beta n$ for some $\beta \in (0, 1)$.

To estimate Λ , we propose to use the *Forward Stepwise and Cut* (FSC) estimator.

Goal of this talk:

- to present an efficient estimator of the set of relevant lags Λ, based on a sample X_{1:n} of a MTD model with order d.
- ▶ to provide some theoretical guarantees in the high-dimensional regime $\Lambda = \Lambda_n$ and $d = d_n = \beta n$ for some $\beta \in (0, 1)$.

To estimate Λ , we propose to use the *Forward Stepwise and Cut* (FSC) estimator.

For a sample
$$X_{1:n}$$
, integer $m < n$, $S \subseteq \{-d, \dots, -1\}$ and $x_S \in \{0,1\}^{S}$, let

$$\hat{p}_{m,n}(x_{\mathcal{S}}) = egin{cases} rac{N_{m,n}(x_{\mathcal{S}},1)}{ar{N}_{m,n}(x_{\mathcal{S}})}, ext{ if } ar{N}_{m,n}(x_{\mathcal{S}}) > 0, \ 1/2, ext{ otherwise} \end{cases},$$

In the definition of $\hat{p}_{m,n}(x_S)$ the countings are over $X_{m+1:n}$.

FSC estimator

The FSC estimator is defined as follows.

Step 1 (FS). From $X_{1:m}$, build a random set \hat{S}_m such that $\Lambda \subseteq \hat{S}_m$ with high probability.

FSC estimator

The FSC estimator is defined as follows.

Step 1 (FS). From $X_{1:m}$, build a random set \hat{S}_m such that $\Lambda \subseteq \hat{S}_m$ with high probability. Step 2 (CUT). For each $j \in \hat{S}_m$, remove j from \hat{S}_m only if $|\hat{p}_{m,n}(x_{\hat{S}_m}) - \hat{p}_{m,n}(y_{\hat{S}_m})| < t_{m,n}(x_{\hat{S}_m}, y_{\hat{S}_m}),$ for all $x_{\hat{S}_m}, y_{\hat{S}_m} \in A^{\hat{S}_m}$ s.t. $x_k = y_k$ for all $k \in \hat{S}_m \setminus \{j\}.$

FSC estimator

The FSC estimator is defined as follows.

Step 1 (FS). From $X_{1:m}$, build a random set \hat{S}_m such that $\Lambda \subseteq \hat{S}_m$ with high probability.

Step 2 (CUT). For each $j \in \hat{S}_m$, remove j from \hat{S}_m only if

$$|\hat{p}_{m,n}(x_{\hat{S}_m}) - \hat{p}_{m,n}(y_{\hat{S}_m})| < t_{m,n}(x_{\hat{S}_m}, y_{\hat{S}_m}),$$

for all $x_{\hat{S}_m}, y_{\hat{S}_m} \in A^{\hat{S}_m} \ s.t. \ x_k = y_k$ for all $k \in \hat{S}_m \setminus \{j\}$. Output $\hat{\Lambda}_n = All$ lags not removed in the CUT step.

Choice of the random threshold

For
$$S \subseteq \{-d, ..., -1\}$$
, $x_S \in \{0, 1\}^S$, we take $t_{m,n}(x_S, y_S) = s_{m,n}(x_S) + s_{m,n}(y_S)$, where

$$s_{m,n}(x_S) = \sqrt{\frac{2\alpha(1+\varepsilon)V_{m,n}(x_S)}{\bar{N}_{m,n}(x_S)}} + \frac{2\alpha}{3\bar{N}_{m,n}(x_S)},$$

with lpha, arepsilon > 0, $\mu \in$ (0,3) s.t. $\mu > \psi(\mu) = e^{\mu} - 1 - \mu$ and

$$V_{m,n}(x_S) = \frac{\mu}{\mu - \psi(\mu)} \hat{p}_{m,n}(x_S) + \frac{\alpha}{\bar{N}_{m,n}(x_S)(\mu - \psi(\mu))}$$

Choice of the random threshold

For
$$S \subseteq \{-d, ..., -1\}$$
, $x_S \in \{0, 1\}^S$, we take $t_{m,n}(x_S, y_S) = s_{m,n}(x_S) + s_{m,n}(y_S)$, where

$$s_{m,n}(x_S) = \sqrt{rac{2lpha(1+arepsilon)V_{m,n}(x_S)}{ar{N}_{m,n}(x_S)}} + rac{2lpha}{3ar{N}_{m,n}(x_S)},$$

with lpha, arepsilon > 0, $\mu \in$ (0,3) s.t. $\mu > \psi(\mu) = e^{\mu} - 1 - \mu$ and

$$V_{m,n}(x_S) = \frac{\mu}{\mu - \psi(\mu)} \hat{p}_{m,n}(x_S) + \frac{\alpha}{\bar{N}_{m,n}(x_S)(\mu - \psi(\mu))}.$$

The choice of $s_{m,n}(x_S)$ is based on a Martingale concentration inequality.

For
$$S \subseteq \{-d, \ldots, -1\}$$
 and $j \notin S$, let $\bar{\nu}_{j,S} = \mathbb{E}\left[|Cov_{X_S}(X_0, X_j)|\right]$.

For
$$S \subseteq \{-d, \ldots, -1\}$$
 and $j \notin S$, let $\bar{\nu}_{j,S} = \mathbb{E}\left[|Cov_{X_S}(X_0, X_j)|\right]$.

Notice that $\max_{j \in S^c} \bar{\nu}_{j,S} = 0$ if $\Lambda \subseteq S$.

For
$$S \subseteq \{-d, \ldots, -1\}$$
 and $j \notin S$, let $\bar{\nu}_{j,S} = \mathbb{E}\left[|Cov_{X_S}(X_0, X_j)|\right]$.

Notice that $\max_{j\in S^c} \bar{\nu}_{j,S} = 0$ if $\Lambda \subseteq S$.

Assumption 1. $\mathbb{P}(X_S = x_S) > 0$ for all $S \subseteq \{-d, \ldots, -1\}$ and $x_S \in \{0, 1\}^S$.

For
$$S \subseteq \{-d, \ldots, -1\}$$
 and $j \notin S$, let $\bar{\nu}_{j,S} = \mathbb{E}\left[|Cov_{X_S}(X_0, X_j)|\right]$.

Notice that $\max_{j \in S^c} \bar{\nu}_{j,S} = 0$ if $\Lambda \subseteq S$.

Assumption 1. $\mathbb{P}(X_S = x_S) > 0$ for all $S \subseteq \{-d, \ldots, -1\}$ and $x_S \in \{0, 1\}^S$.

Proposition 1. Under Assumption 1 there exists $\kappa > 0$ such that the following property holds: for all $S \subseteq \{-d, \ldots, -1\}$ with $\Lambda \not\subseteq S$, it holds that

$$\max_{j\in S^c}\bar{\nu}_{j,S}\geq \max_{j\in\Lambda\backslash S}\bar{\nu}_{j,S}\geq \kappa$$

Denote $\hat{\nu}_{m,j,S}$ the empirical estimate of $\bar{\nu}_{j,S}$ computed from $X_{1:m}$.

Denote $\hat{\nu}_{m,j,S}$ the empirical estimate of $\bar{\nu}_{j,S}$ computed from $X_{1:m}$.

To build \hat{S}_m , we do as follows. Fix $0 \le \ell \le d$. 1. Set $\hat{S}_m = \emptyset$. 2. While $|\hat{S}_m| < \ell$, compute $j \in \arg \max_{k \in \hat{S}_m^c} \hat{\nu}_{m,k,\hat{S}_m}$ and include j in \hat{S}_m .

Theorem. Take m = n/2 and assume $d = \beta m$ for $\beta \in (0, 1)$ and suppose $\lambda_0 > 0$, $0 < p_0 < 1$ and that the following conditions hold:

Theorem. Take m = n/2 and assume $d = \beta m$ for $\beta \in (0, 1)$ and suppose $\lambda_0 > 0$, $0 < p_0 < 1$ and that the following conditions hold:

► $\exists \ \Gamma_1 \in (0,1]$ s.t. for all $S \subset \{-d, \ldots, -1\}$ such that $\Lambda \not\subseteq S$ and $k \in \Lambda \setminus S$,

$$\max_{x_{\mathcal{S}}\in\{0,1\}^{\mathcal{S}}}\sum_{j\in\Lambda\setminus\mathcal{S}\cup\{k\}}\frac{\delta_{j}}{\delta_{k}}|\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=0)-\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=1)|\leq(1-\mathsf{\Gamma}_{1}).$$

Theorem. Take m = n/2 and assume $d = \beta m$ for $\beta \in (0, 1)$ and suppose $\lambda_0 > 0$, $0 < p_0 < 1$ and that the following conditions hold:

►
$$\exists \Gamma_1 \in (0,1]$$
 s.t. for all $S \subset \{-d, \ldots, -1\}$ such that $\Lambda \not\subseteq S$ and $k \in \Lambda \setminus S$,

 $\max_{x_{\mathcal{S}}\in\{0,1\}^{\mathcal{S}}}\sum_{j\in\Lambda\setminus\mathcal{S}\cup\{k\}}\frac{o_{j}}{\delta_{k}}|\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=0)-\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=1)|\leq(1-\mathsf{\Gamma}_{1}).$

► ∃
$$\Gamma_2 \in (0,1]$$
 s.t. for all $S \subset \{-d, \ldots, -1\}$ such that $\Lambda \subset S$ and $k \notin \Lambda$,

$$\sum_{j \in \Lambda \setminus S} \max_{x_S \in \{0,1\}^S} |\mathbb{P}_{x_S}(X_k = 1 | X_j = 0) - \mathbb{P}_{x_S}(X_k = 1 | X_j = 1)| \leq \Gamma_2.$$

Suppose also $|\Lambda| \leq L$ with L known and let $\hat{\Lambda}_n$ be the FSC estimator constructed with parameters $\ell = L$ and $\alpha = (1 + \eta) \log(n)$ for $\eta > 0$.

Theorem. Take m = n/2 and assume $d = \beta m$ for $\beta \in (0, 1)$ and suppose $\lambda_0 > 0$, $0 < p_0 < 1$ and that the following conditions hold:

►
$$\exists \Gamma_1 \in (0,1] \text{ s.t. for all } S \subset \{-d, \ldots, -1\} \text{ such that } \Lambda \not\subseteq S \text{ and } k \in \Lambda \setminus S,$$

$$\max_{x_{\mathcal{S}}\in\{0,1\}^{\mathcal{S}}}\sum_{j\in\Lambda\setminus\mathcal{S}\cup\{k\}}\frac{o_{j}}{\delta_{k}}|\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=0)-\mathbb{P}_{x_{\mathcal{S}}}(X_{j}=1|X_{k}=1)|\leq(1-\mathsf{\Gamma}_{1}).$$

► ∃
$$\Gamma_2 \in (0,1]$$
 s.t. for all $S \subset \{-d, \ldots, -1\}$ such that $\Lambda \subset S$ and $k \notin \Lambda$,

$$\sum_{j \in \Lambda \setminus S} \max_{x_S \in \{0,1\}^S} |\mathbb{P}_{x_S}(X_k = 1 | X_j = 0) - \mathbb{P}_{x_S}(X_k = 1 | X_j = 1)| \leq \Gamma_2.$$

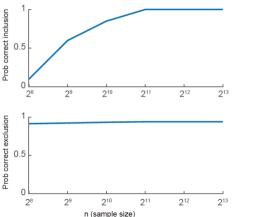
Suppose also $|\Lambda| \leq L$ with L known and let $\hat{\Lambda}_n$ be the FSC estimator constructed with parameters $\ell = L$ and $\alpha = (1 + \eta) \log(n)$ for $\eta > 0$. Then \exists a constant C > 0 such that $\mathbb{P}(\hat{\Lambda}_n \neq \Lambda) \rightarrow 0$ as $n \rightarrow \infty$,

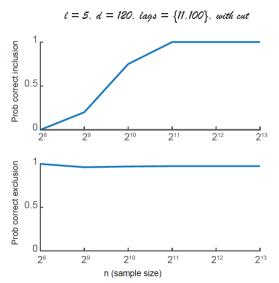
as long as

$$\min_{j\in\Lambda}\delta_j^2\geq C\frac{\log(n)}{n}.$$

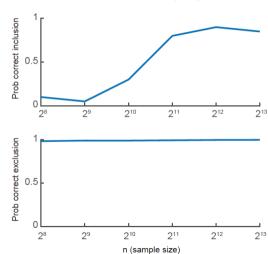
Simulations: FSC estimator

l = 5, d = 50, lags = {11.21}, with cut





Simulations: FSC estimator



Simulations: transition probability estimation

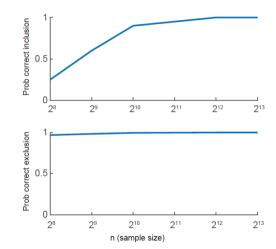
MTD model used:
$$p(x) = \lambda_0 p_0 + \lambda_i p_i(x_i) + \lambda_j p_j(x_j)$$
 where $\lambda_0 = 0.2$, $p_0 = 0.5$, $\lambda_i = \lambda_j = 0.4$, $1 - p_i(0) = p_i(1) = 1 - p_j(0) = p_j(1) = 0.7$.

For each choice of i, j, d, and n we simulated 100 realizations. For each realization, we estimated the transition probability $p(0|0^d)$.

Model parameter			Method	Sample size (n)					
i	j	d		256	512	1024	2048	4096	8192
1	5	5	FSC(2)	0.0774	0.0682	0.0506	0.0286	0.0174	0.0133
1	5	5	FSC(5)	0.0745	0.0835	0.0602	0.0426	0.0222	0.0129
1	5	5	PCP	0.0965	0.0786	0.0577	0.0432	0.0242	0.0131
1	5	5	Naive	0.1518	0.0933	0.0624	0.0455	0.0340	0.0252
1	5	10	FSC(5)	0.0836	0.0842	0.0659	0.0425	0.0228	0.0141
1	10	15	FSC(5)	0.0864	0.0781	0.0641	0.0438	0.0249	0.0151
1	15	20	FSC(5)	0.0682	0.0802	0.0778	0.0534	0.0285	0.0138
11	100	120	FSC(5)	-	-	0.0838	0.0647	0.0312	0.0169
1	10	n/8	FSC(5)	0.0563	0.0543	0.0780	0.0698	0.0504	0.0105

Simulations: FSC without CUT





We could estimate Λ by

$$\hat{\Lambda}_{BIC} = \arg\min_{S \in \mathcal{P}(\{-d,\dots,-1\})} \left\{ -\log ML_S(X_1,\dots,X_n) + \frac{(3|\Lambda|+1)}{2}\log(n) \right\}.$$

Can we compute $\hat{\Lambda}_{BIC}$ efficiently? The models are not nested!

We could estimate Λ by

$$\hat{\Lambda}_{BIC} = \arg\min_{S \in \mathcal{P}(\{-d,...,-1\})} \left\{ -\log ML_S(X_1,\ldots,X_n) + \frac{(3|\Lambda|+1)}{2}\log(n) \right\}.$$

Can we compute $\hat{\Lambda}_{BIC}$ efficiently? The models are not nested!

What about multivariate MTD models?